

FIG. 1

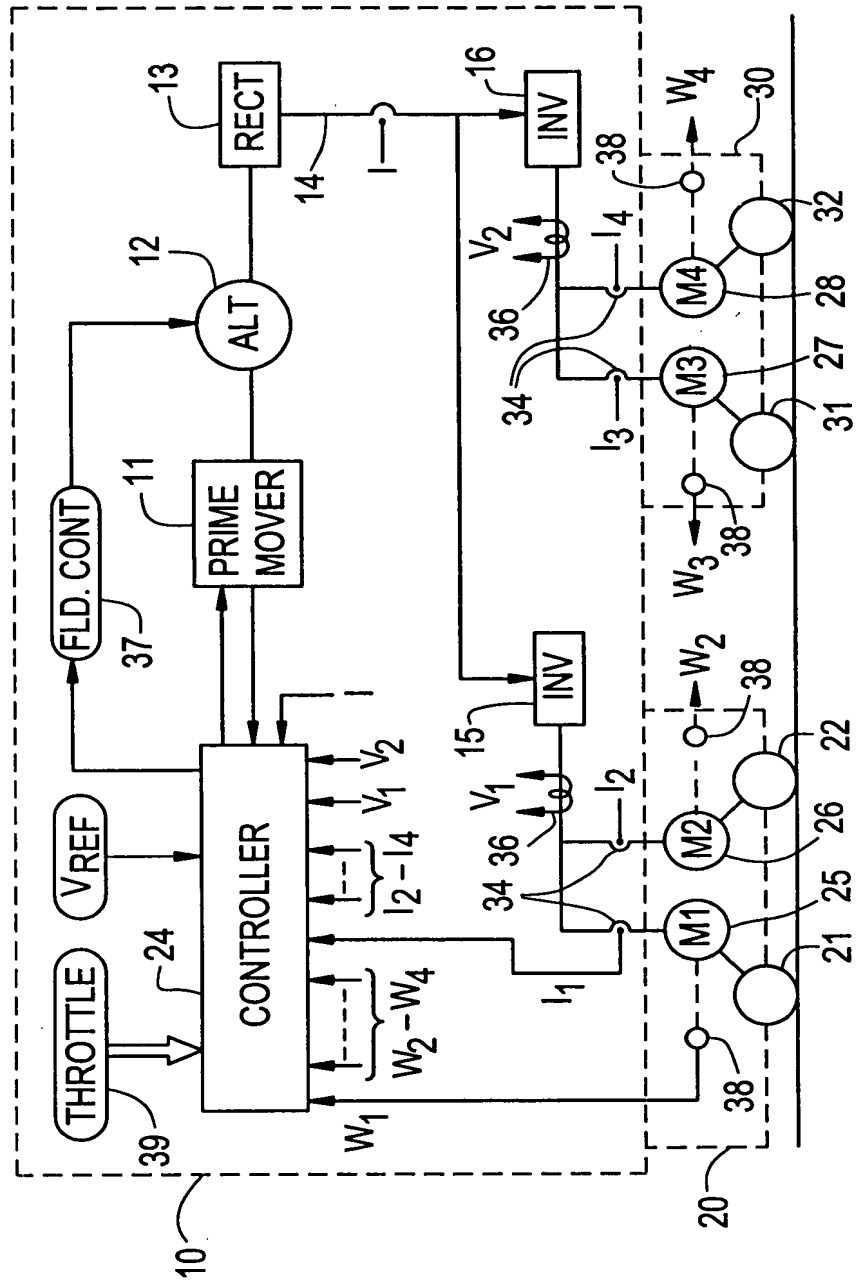
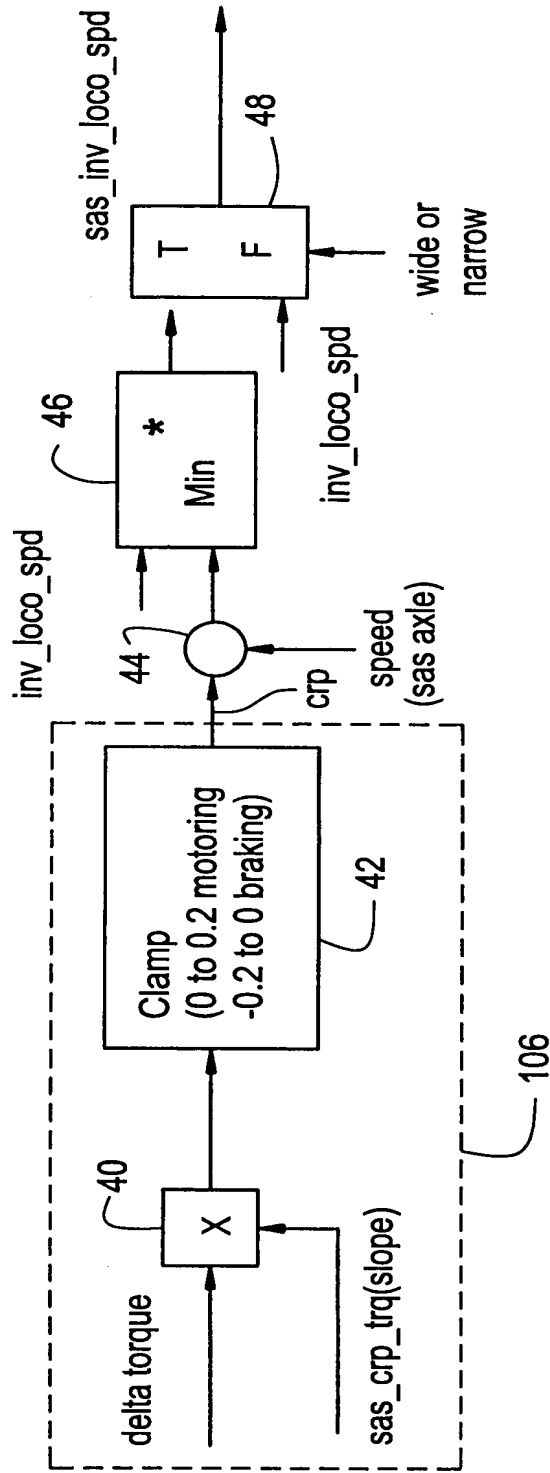


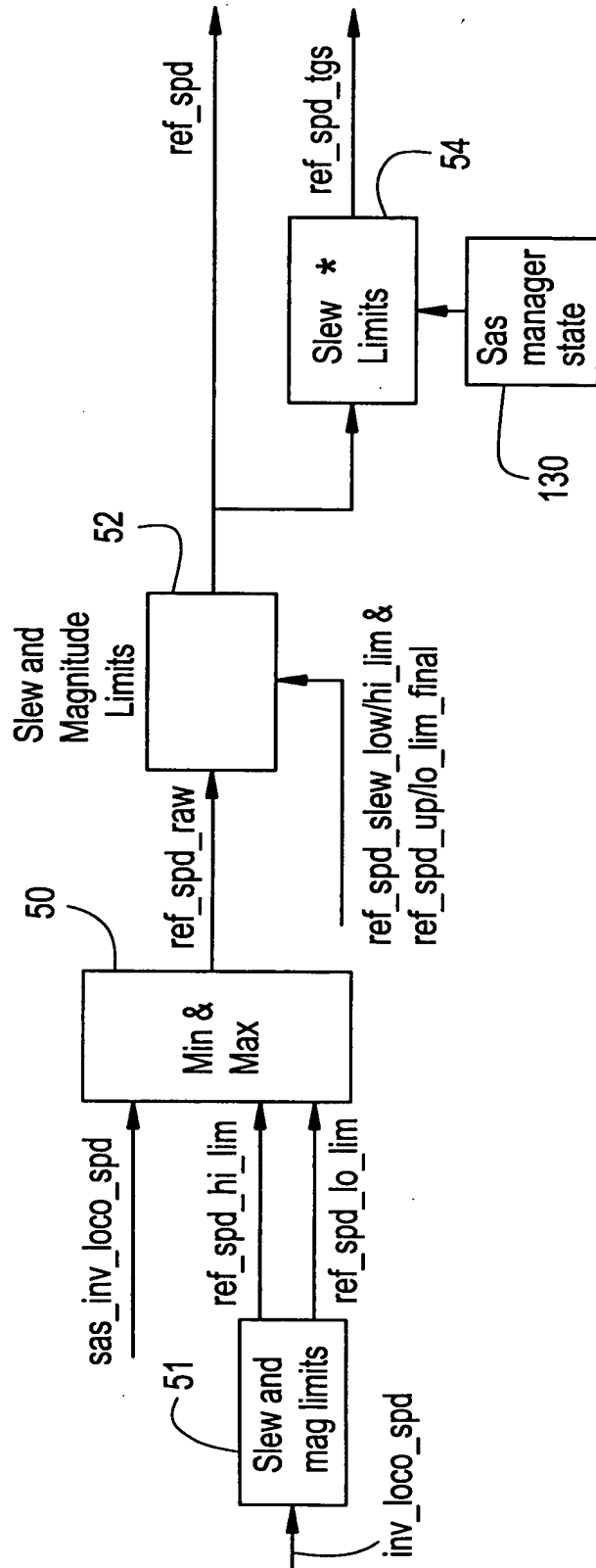


FIG. 2B



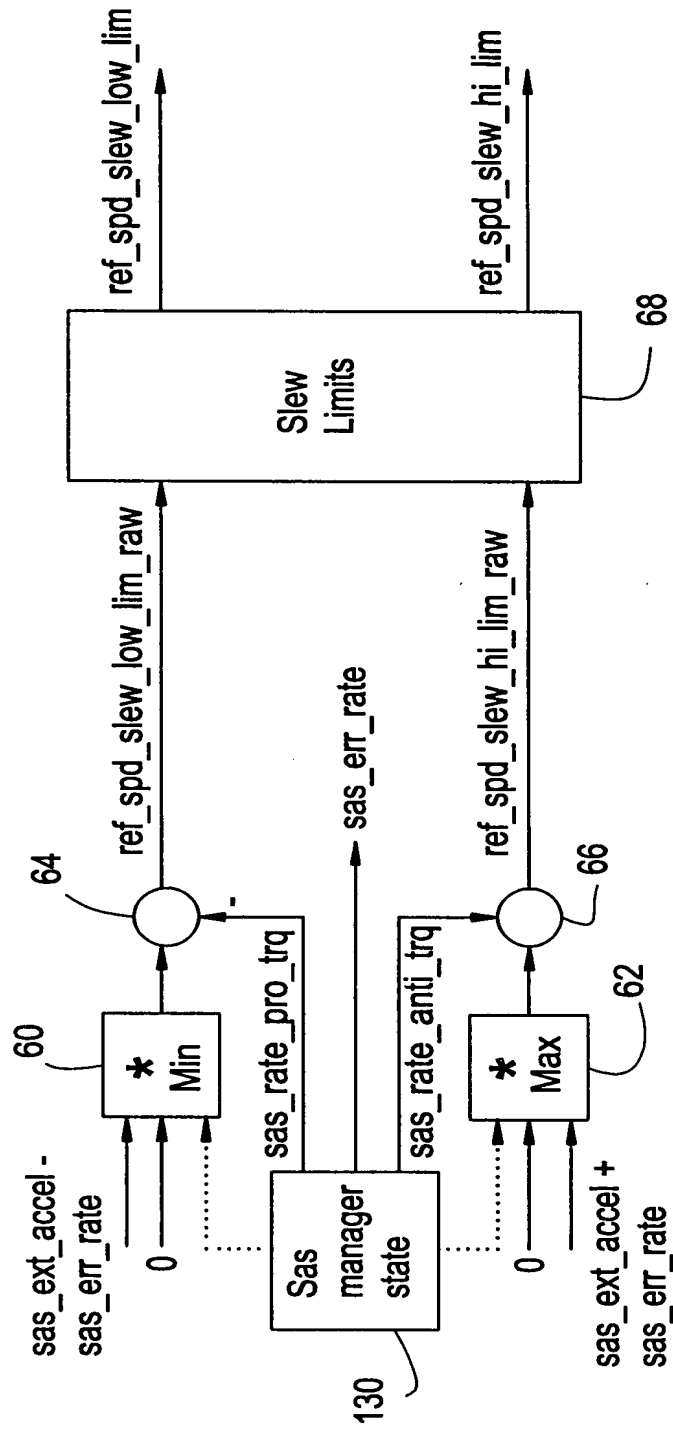
\* Min if motoring &  
Max if Braking

FIG. 2C



\* no limits wide or narrow  
else tight limits for synchronous  
slip protection

FIG. 2D



\* set output to 0 if not wide or narrow

FIG. 3

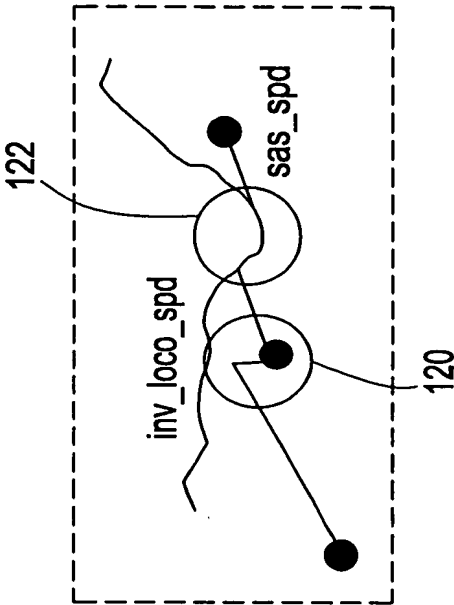


FIG. 4

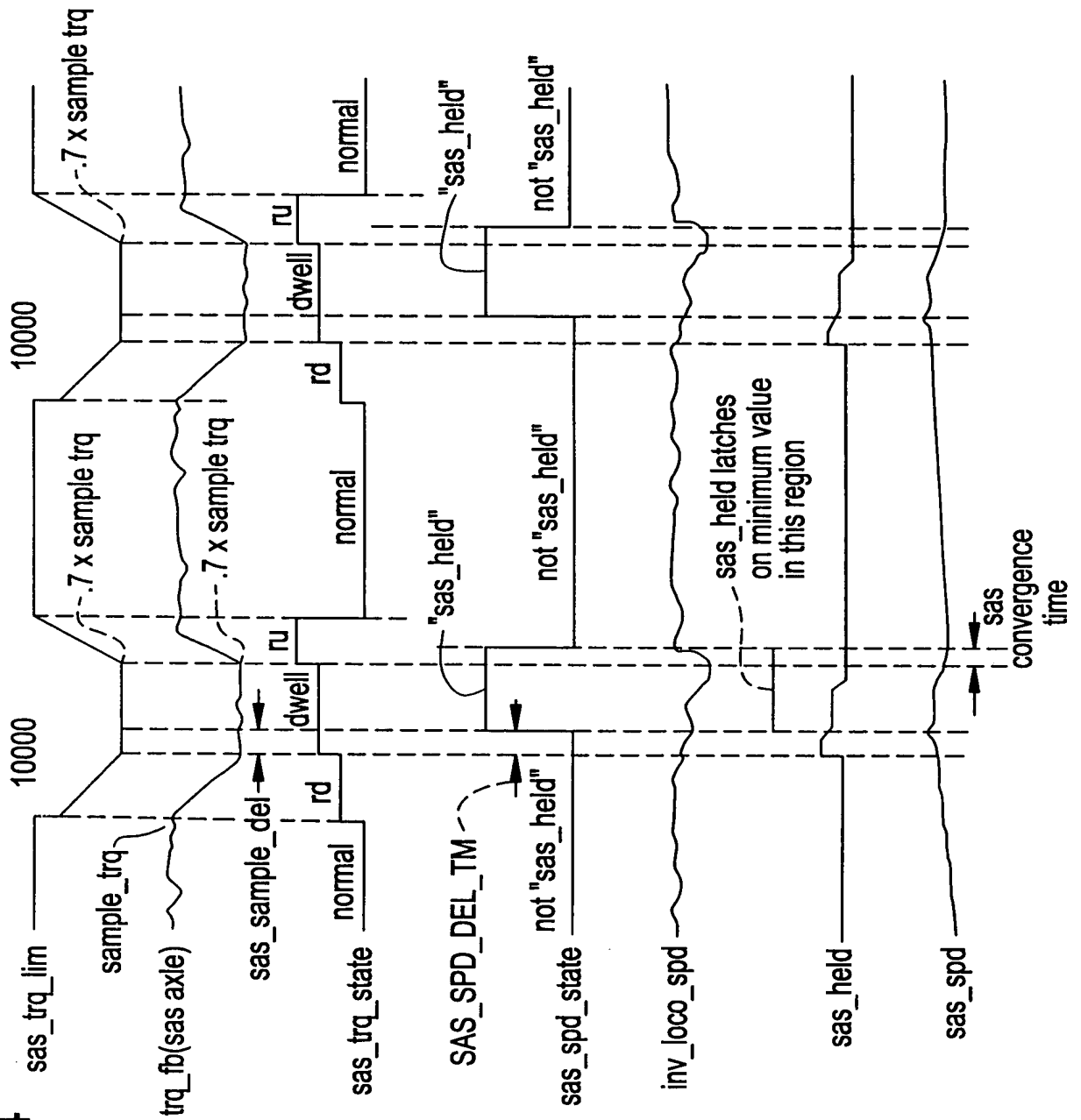


FIG. 5

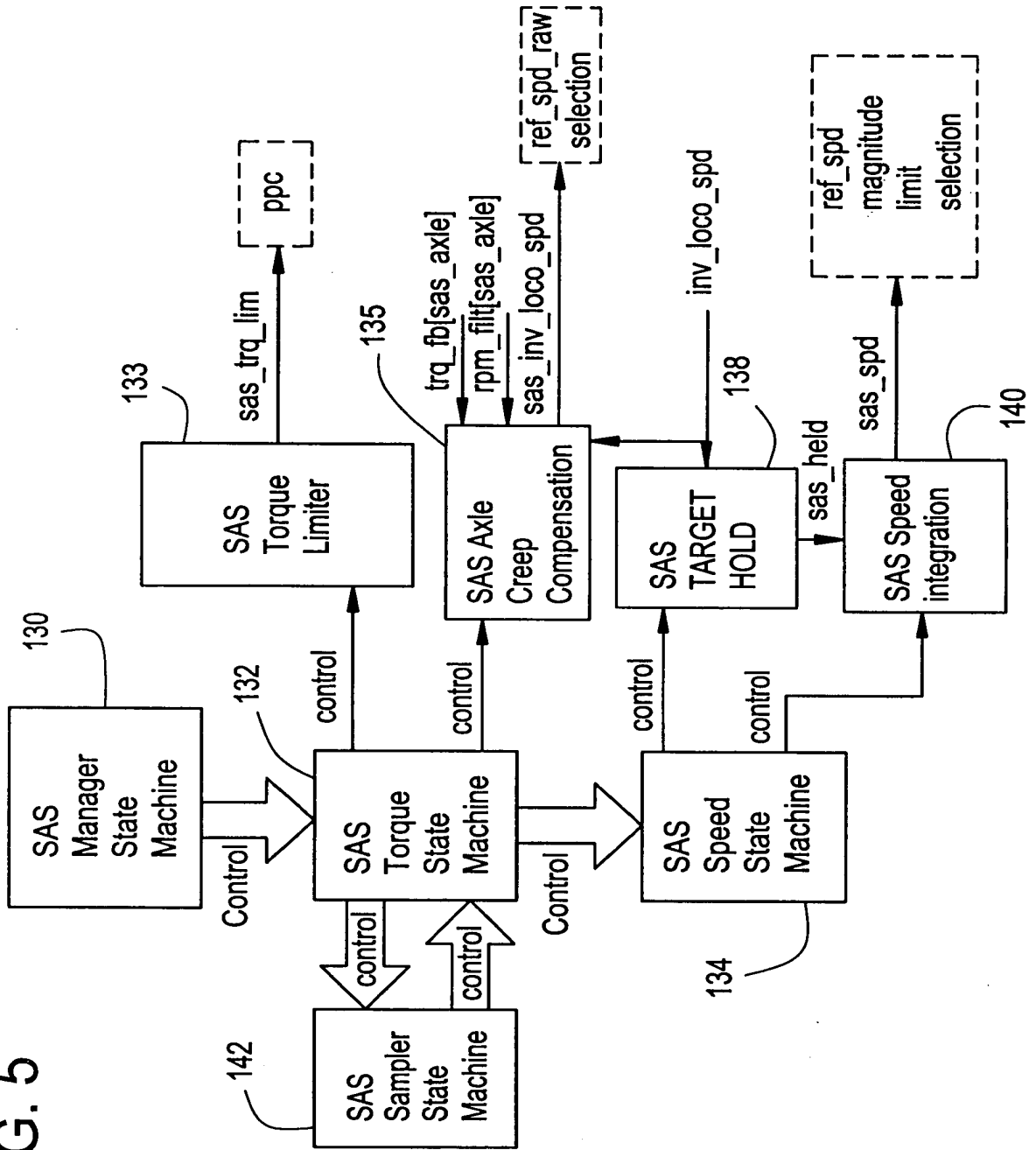
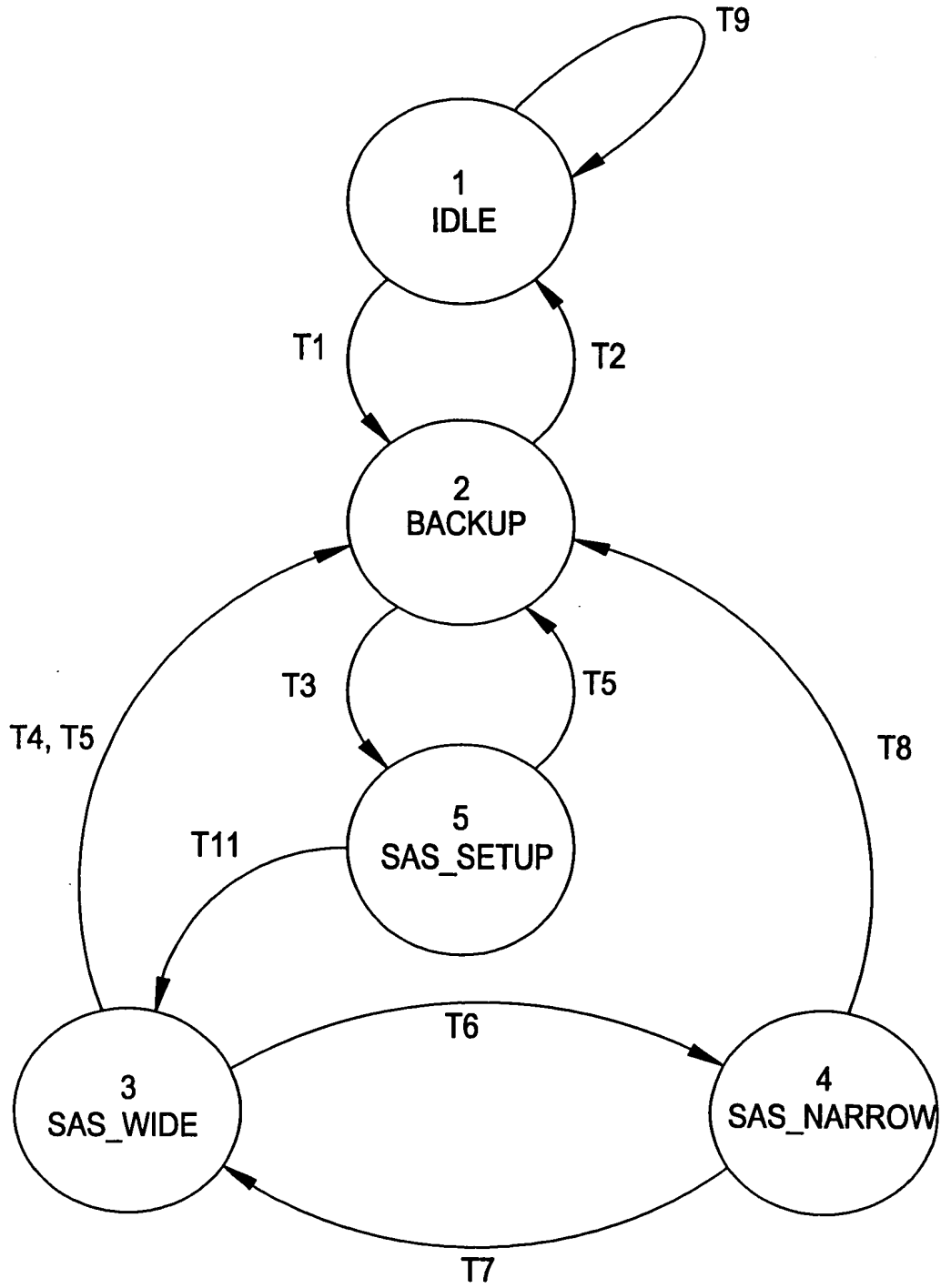




FIG. 6



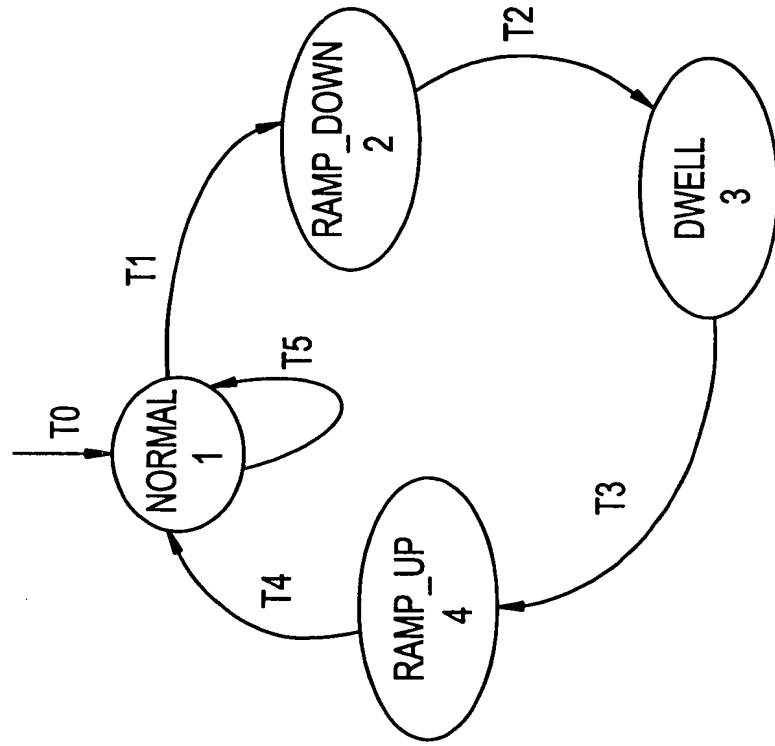


FIG. 7

FIG. 8

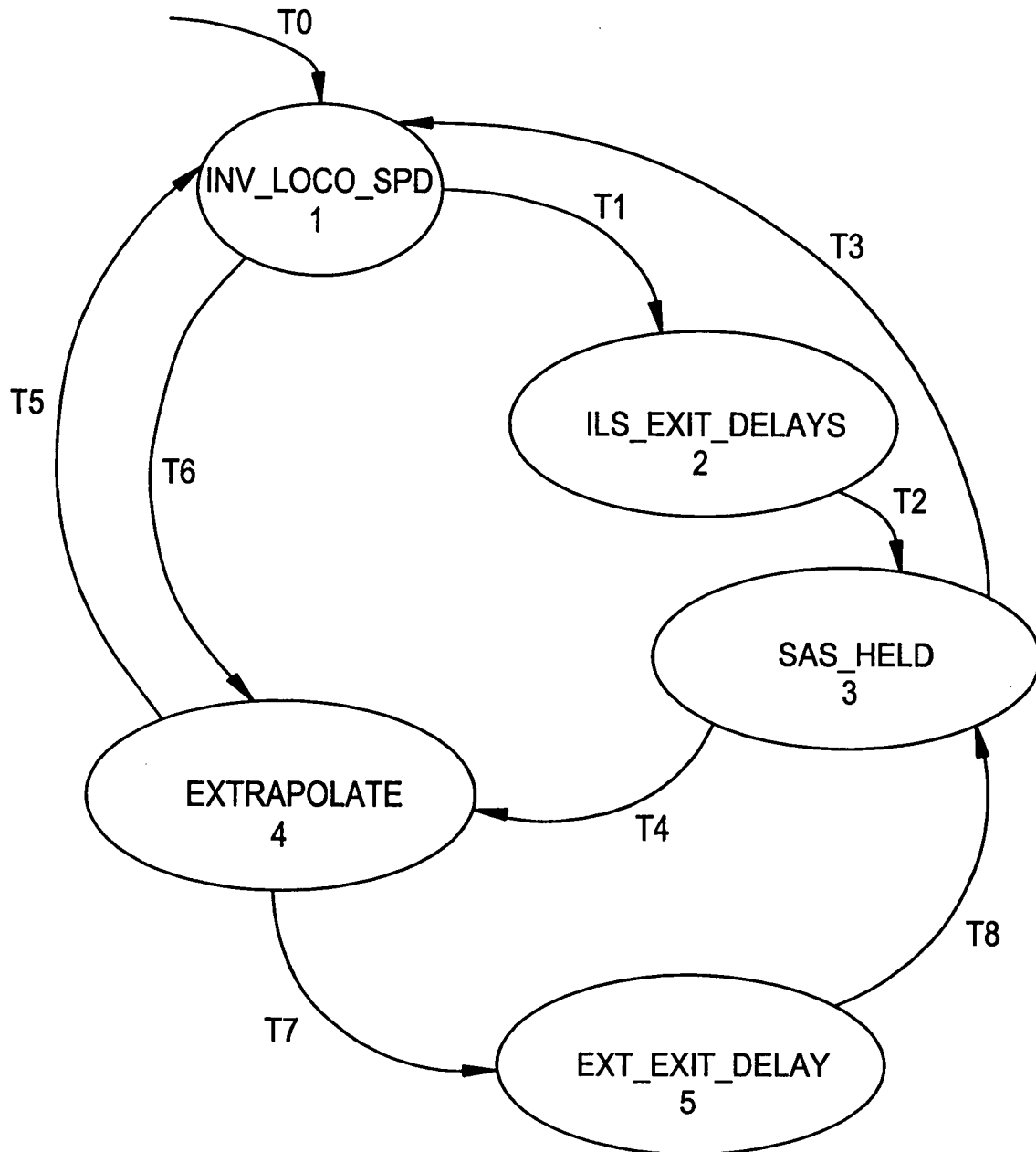


FIG. 9

